



# VERIFICATION OF EDDY-PROPERTIES IN OPERATIONAL OCEANOGRAPHIC ANALYSIS SYSTEMS

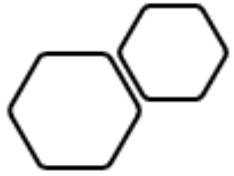
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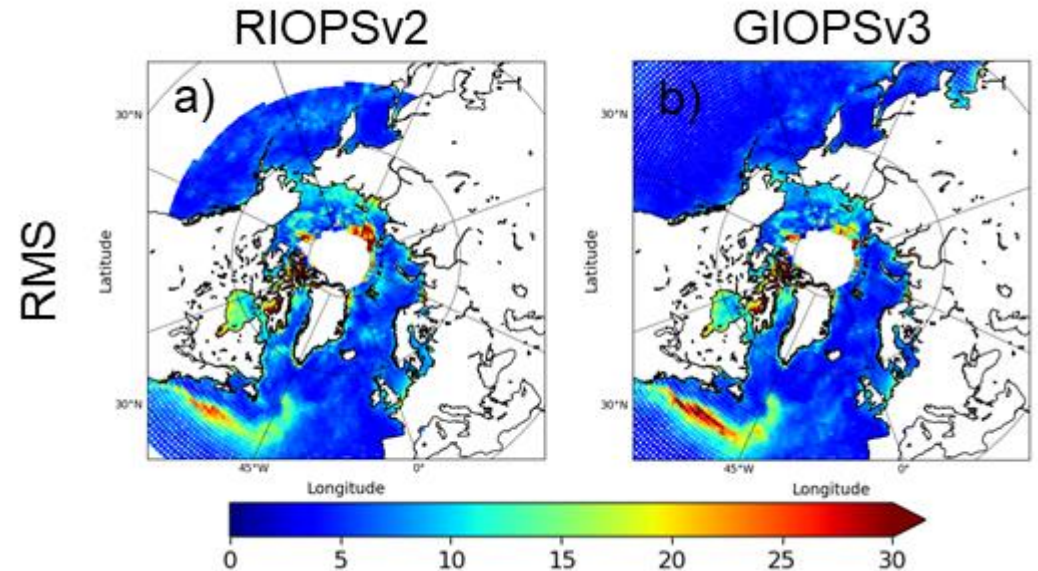
# Background and Motivation

- Many ocean eddy tracking studies have been made:
  - Chelton et al. (2011), Mason et al. (2014), Faghmous et al. (2015), Conti et al. (2016), Pegliasco et al. (2020).
- None have been used before for the verification of mesoscale eddies in ocean forecasts (as is routinely done for tropical cyclones)
  - Eddies important for surface currents and many marine applications.
  - Presence of eddies shown to affect cyclone intensification (Ma et al., 2017).
- Here we use an eddy tracking code to evaluate the representation of actual mesoscale eddies in Operational Global and Regional ECCO analyses.
  - Anticipate that RIOPS will have an improved representation of eddies due to its higher spatial resolution (x3).

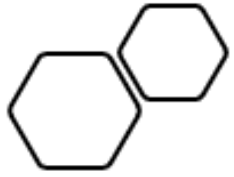
# ECOC Operational Ocean Analysis Systems

- [G,R]IOPS = [Global, Regional] Ice Ocean Prediction System
  - GIOPS = Global 1/4° resolution
  - RIOPS = N.Atl/Arctic/N.Pac 1/12° resolution
- Mercator Ocean Assimilation System (SAM2):
  - Sea surface temperature
  - Temperature and salinity profiles
  - Along-track sea level anomaly from satellite altimeters
- Produce daily ice-ocean analyses from two successive 7-day cycles
  - 3DVAR T/S bias correction, IAU

Somewhat smaller RMS errors in RIOPS over Gulf Stream, but what does this mean in terms of representation of actual eddies?

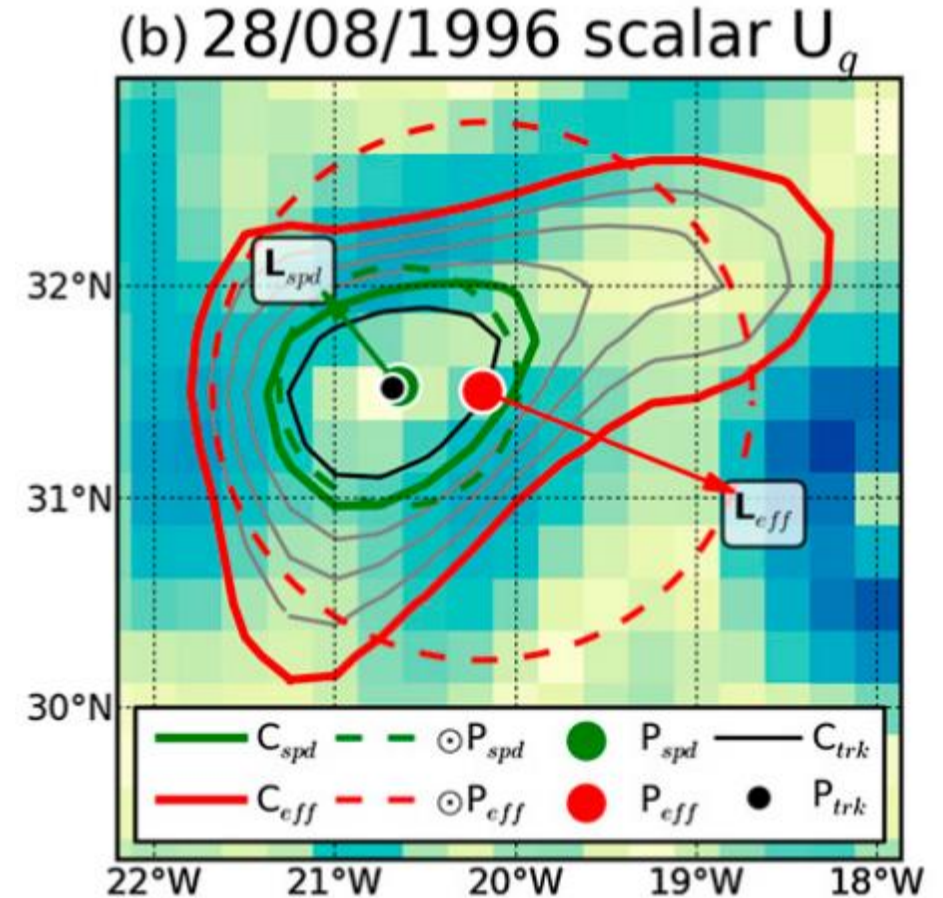


*Innovation statistics of sea level anomaly for the period 2016 to 2019.*

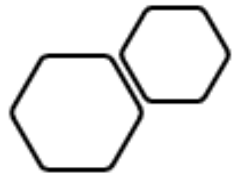


# Eddy Identification

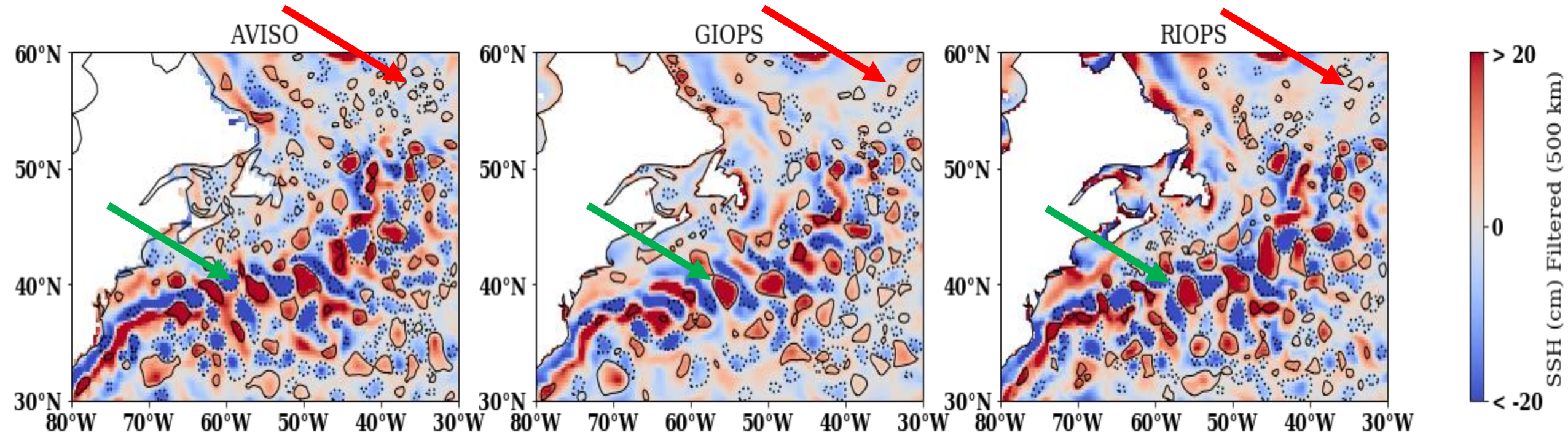
- Used py-eddy-tracker (Mason et al., 2014)
- Identifies closed contours of sea level anomaly (SLA) or absolute dynamic topography (ADT) field.
- For a closed contour to be a valid eddy, it must satisfy the following criteria:
  - Only one maxima (minima) allowed
  - Have between 5 and 2000 pixels
  - Must fit a circle with a maximum of 55% error in area
  - The amplitude must be at least twice the contour interval (i.e. 0.4 cm)



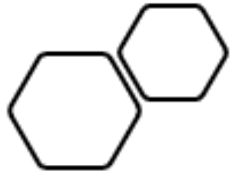
Eddy Identified plotted over  $U$  geostrophic velocity.  
 $C_{eff}$  (red solid contour): Cyclonic eddy  
 $P_{eff}$  (red dot): Centroid of  $C_{eff}$   
 $P_{eff}$  (red dashed contour): Circle with same area as  $C_{eff}$   
Mason et al. (2014)



# Eddy Identification



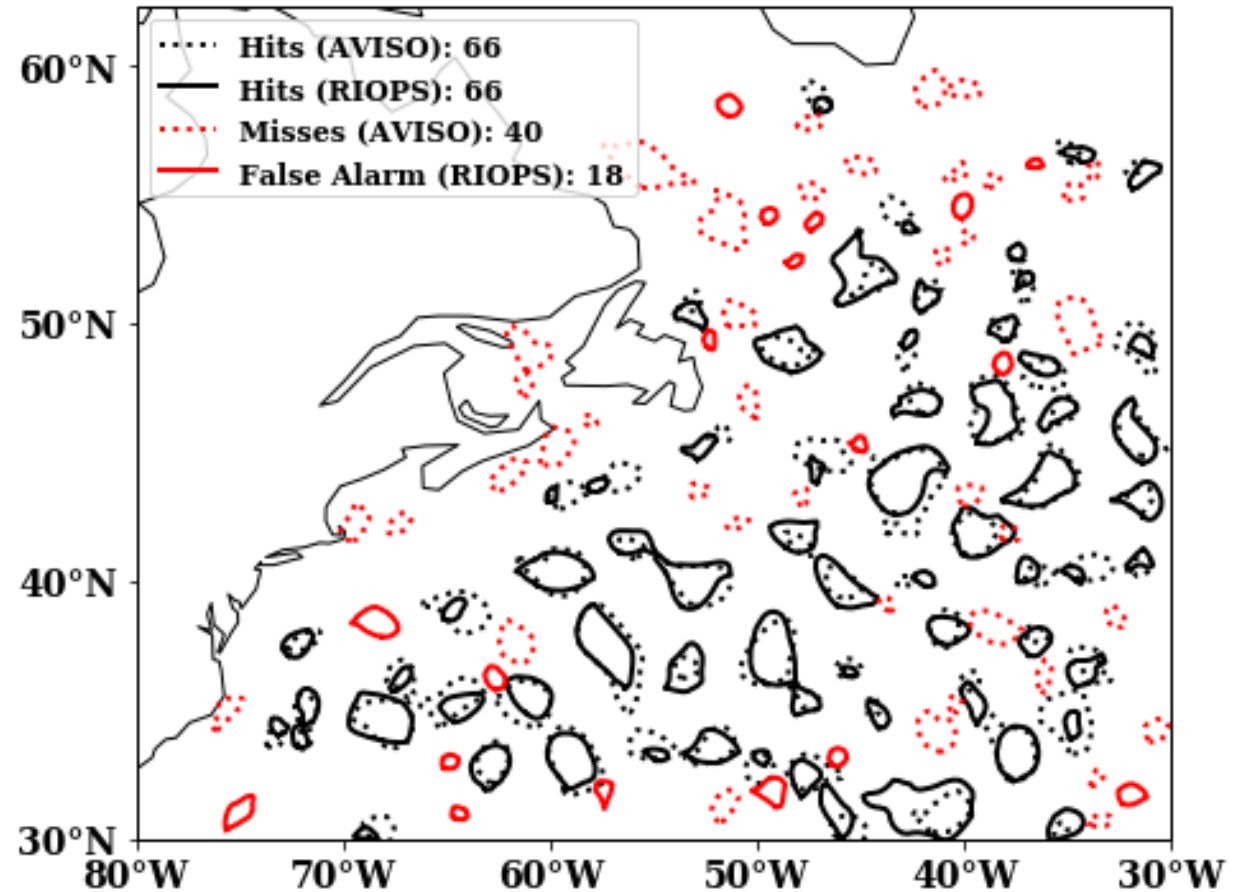
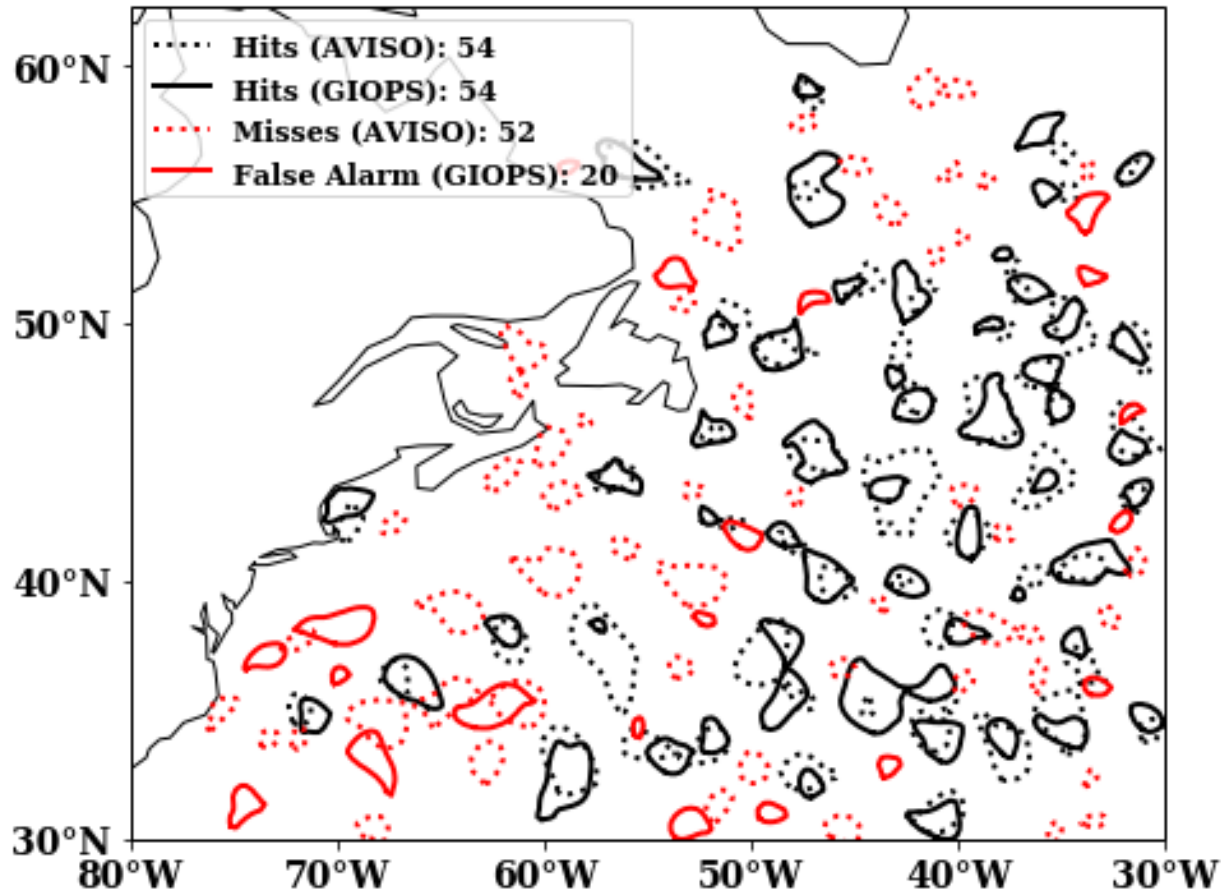
- Anticyclonic (solid) and cyclonic (dotted) eddies contours plotted over filtered SSH (2017-01-01)
- Eddies generally well-identified in all three products
- Correspondence of many of the larger features, but smaller-scale features quite different
  - Shows limit of smallest constrained scales

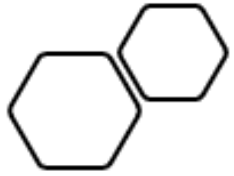


# Eddy Matching

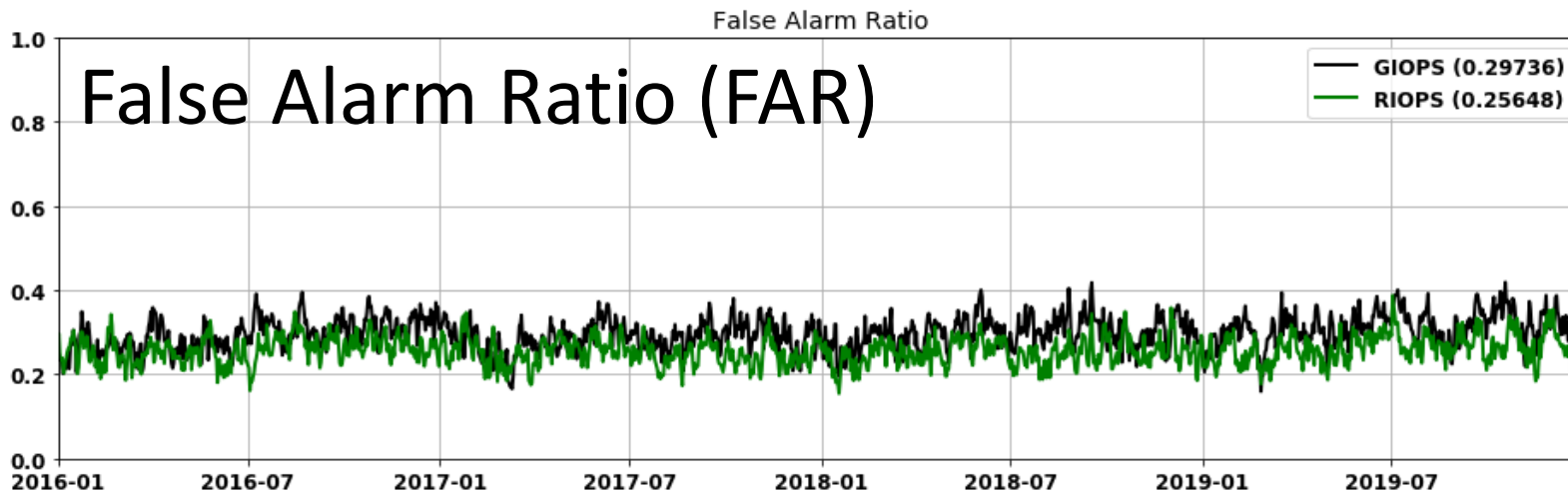
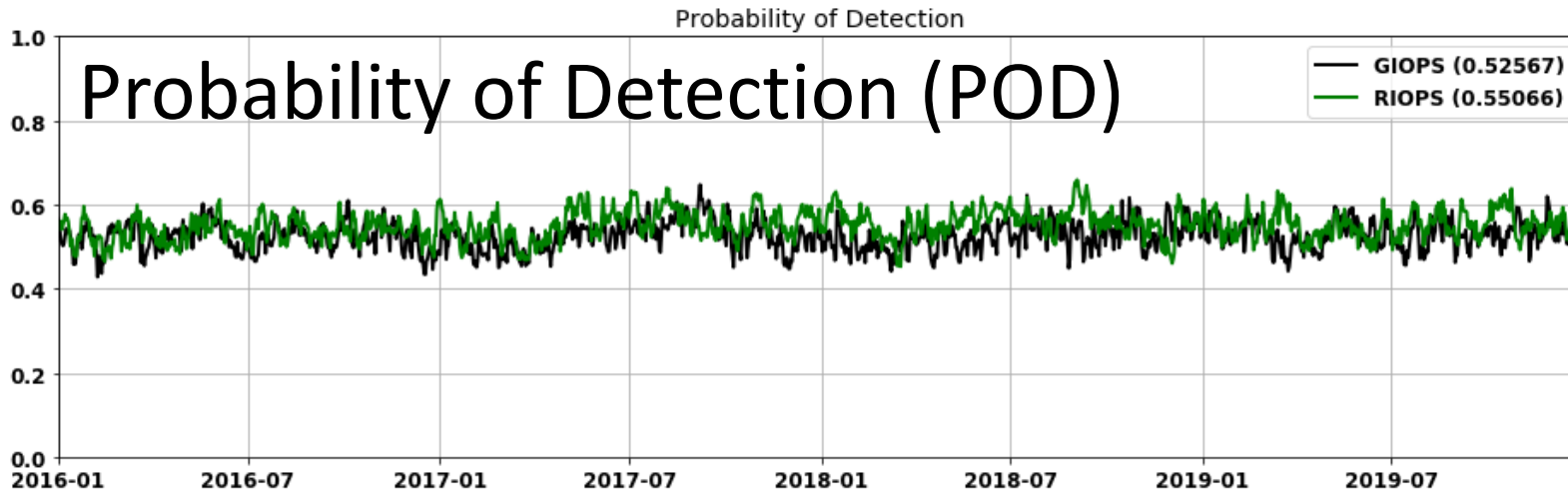
Pair eddies with the lowest cost within 125 km.

Cyclonic Matches (2017-01-01)



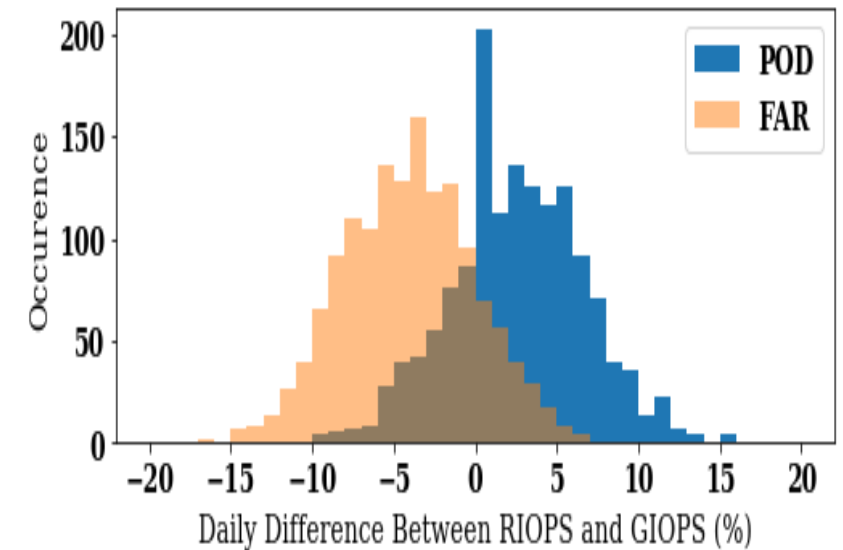


# Eddy Matching



$$POD = \frac{Hits}{Hits + Misses}$$

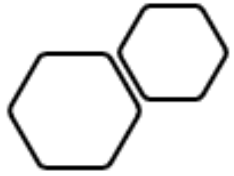
$$FAR = \frac{False\ Alarms}{Hits + False\ Alarms}$$



Mean differences (RIOPS-GIOPS)

POD: 2.3%

FAR: -3.9%

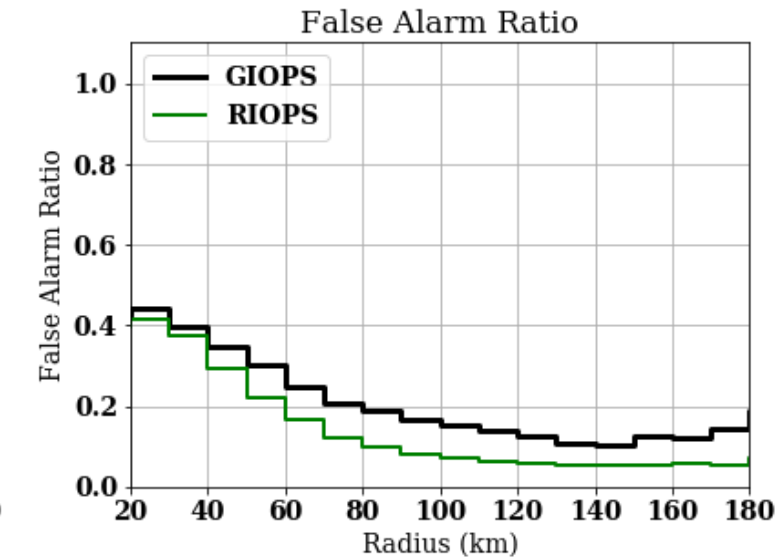
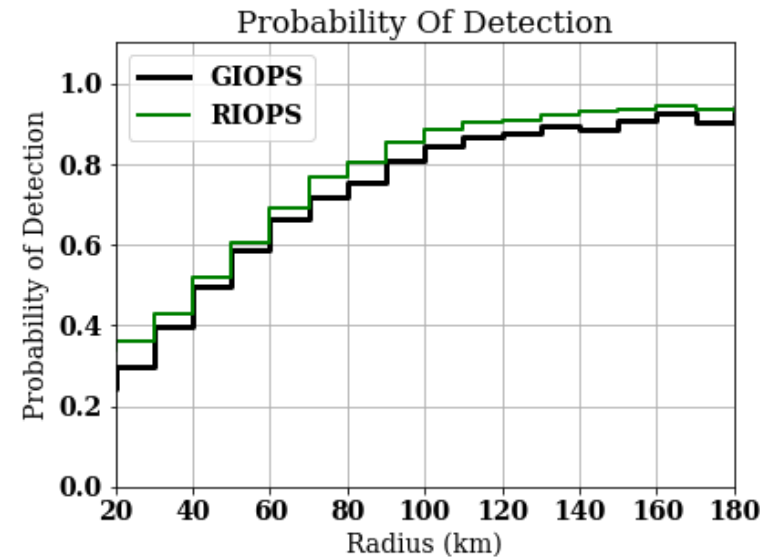
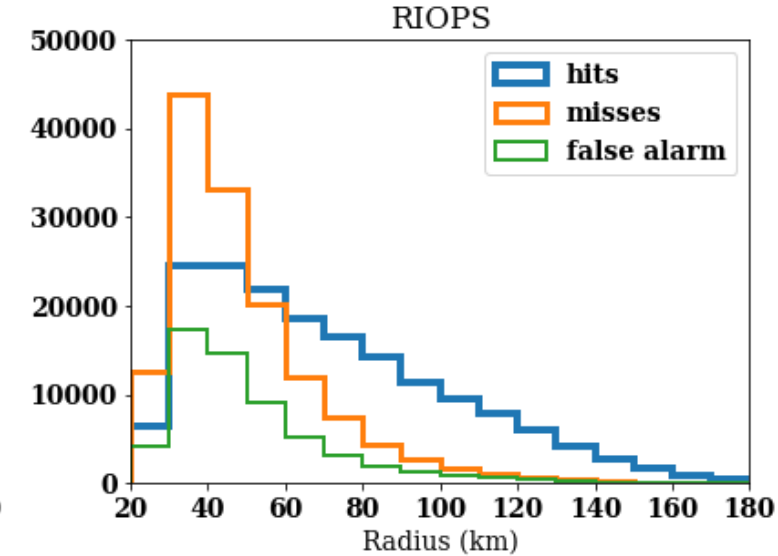
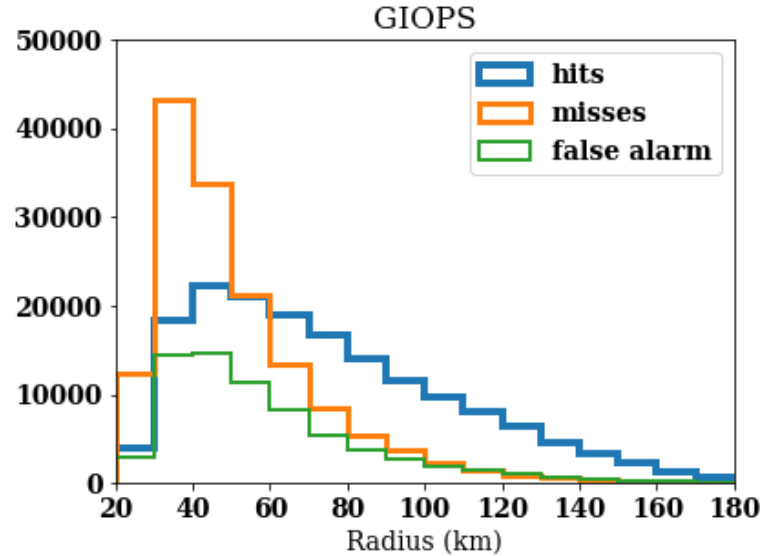


# Eddy Matching – As a Function of Radius

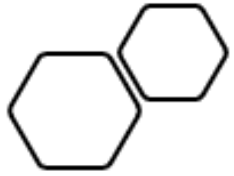
$$POD = \frac{Hits}{Hits + Misses}$$

$$FAR = \frac{False\ Alarms}{Hits + False\ Alarms}$$

- More than half misses and false alarms have a radii less than 50 km.
- Maybe AVISO (altimetry) limited capacity to capture small wavelengths, resulting in more misses at smaller radii, or GIOPS & RIOPS represent less small eddies
- POD increases with size of radii.
- FAR decrease with size of radii.

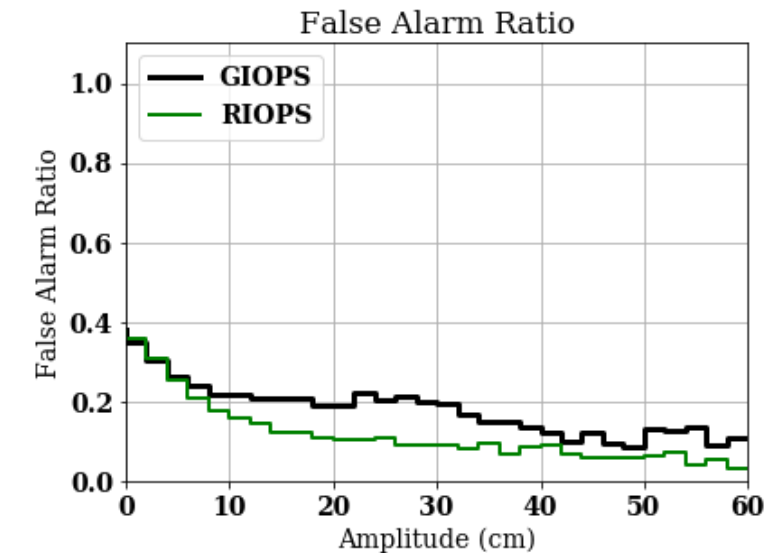
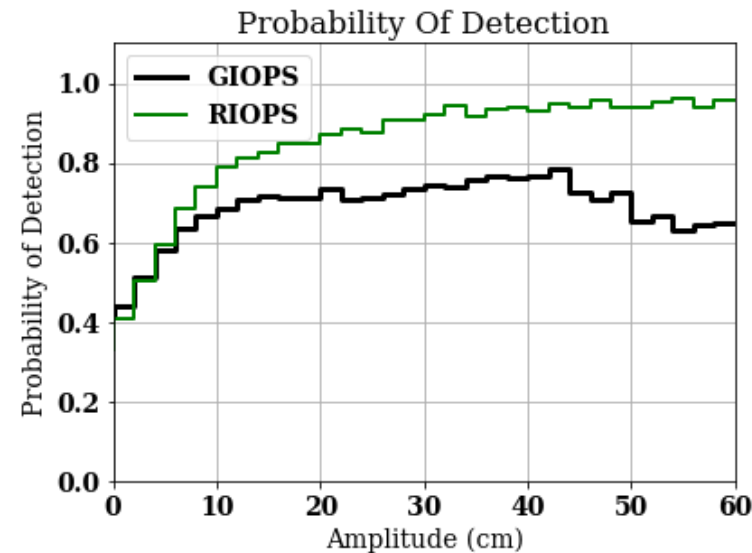
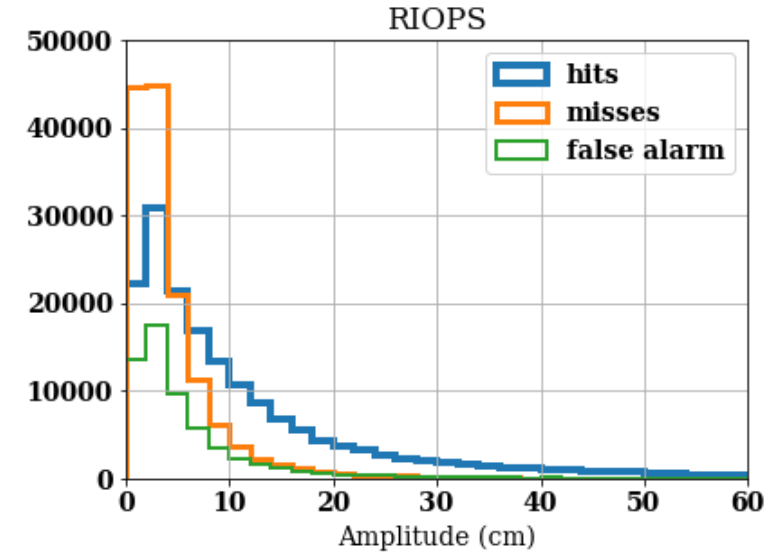
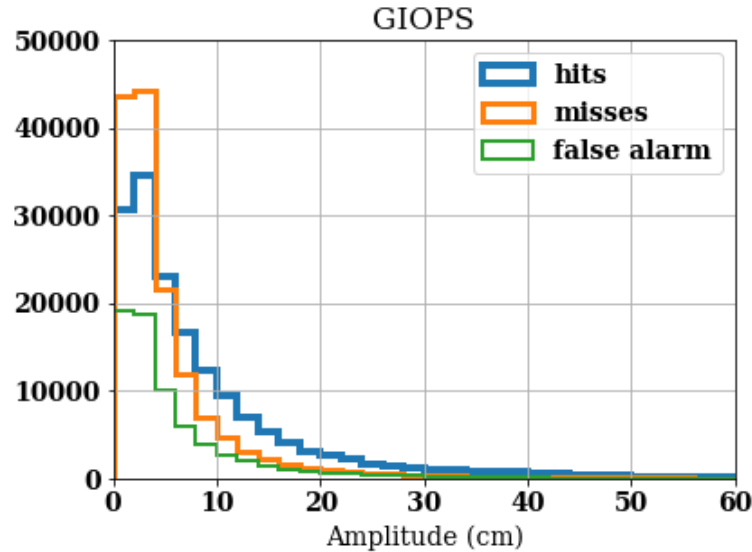


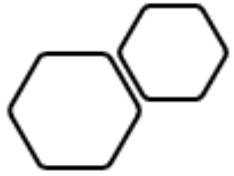




# Eddy Matching – As a function of Amplitude

- POD increases with amplitude
- FAR decrease with amplitude
- Most eddies have small amplitudes (< 10 cm); RIOPS and GIOPS show similar scores
  - Room for improvement!





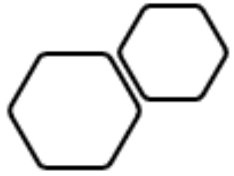
## Generate Scores for Position and Size

Cost of matching

$$cost = \sqrt{\left(\frac{A_1 - A_2}{A_1}\right)^2 + \left(\frac{R_1 - R_2}{R_1}\right)^2 + \left(\frac{distance}{125 km}\right)^2}$$

Where  $A = Amplitude$ ,  $R = Radii$

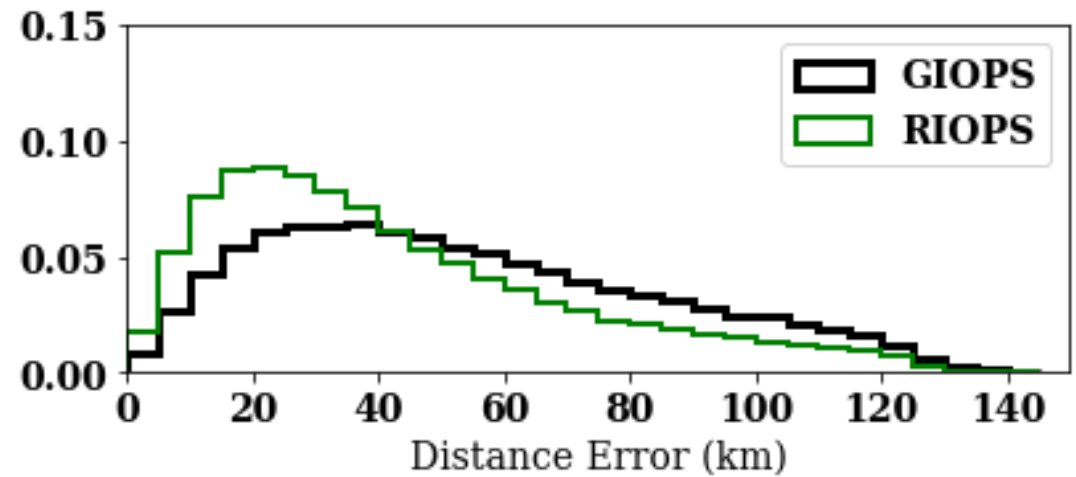
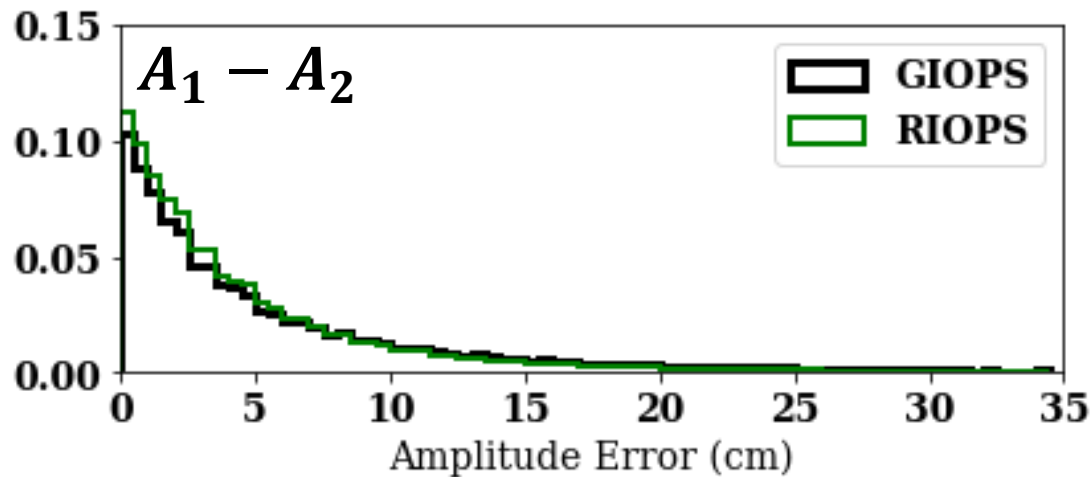
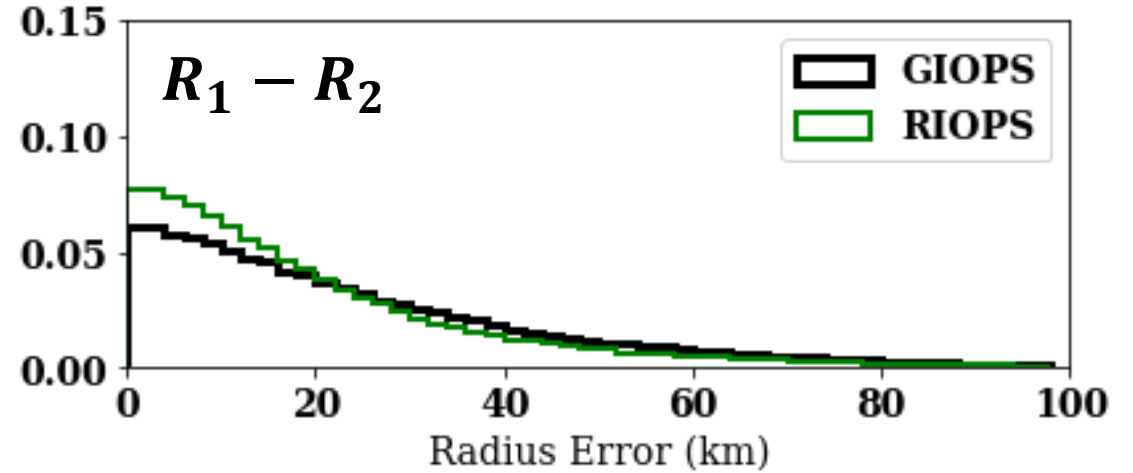
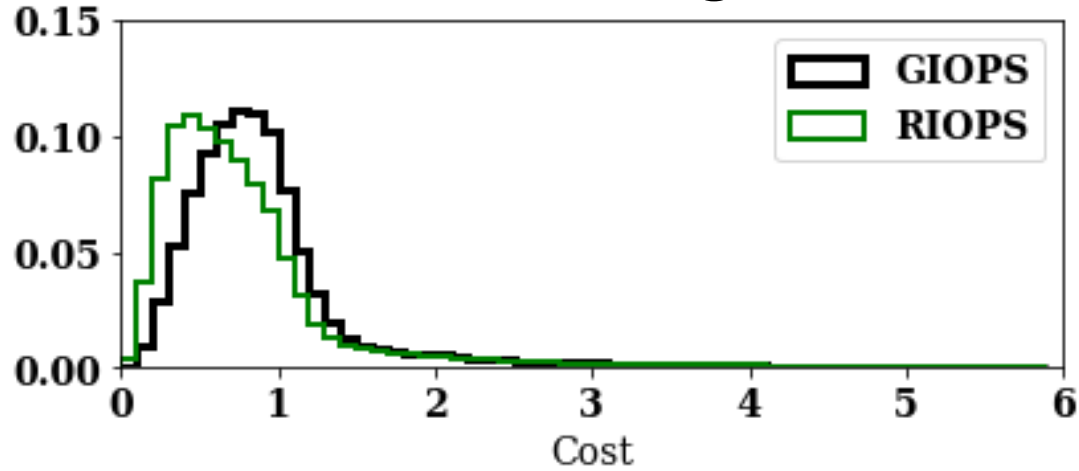
$$cost = \sqrt{\left(\frac{A_1 - A_2}{A_1}\right)^2 + \left(\frac{R_1 - R_2}{R_1}\right)^2 + \left(\frac{distance}{125 km}\right)^2}$$

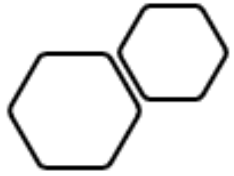


# Generate Scores for Position and Size

## Normalized Histograms

Hits Costs





# Conclusion

Demonstrated that eddy matching is able to detect and quantify the improved representation of eddies in RIOPS as compared to GIOPS

- Improvement in POD (2.3%), FAR (-3.9%)
  - mainly for eddies larger than 50 km radius and 10 cm in amplitude
- Improvement in position and size

## Future work

- Develop methods to objectively identify limits in small-scales
- Apply code to other regions
- Investigate error as a forecast lead-time
- Implement eddy identification in near real time
- Intercomparison with other operational systems (Mercator, UKMET...)

# Acknowledgements

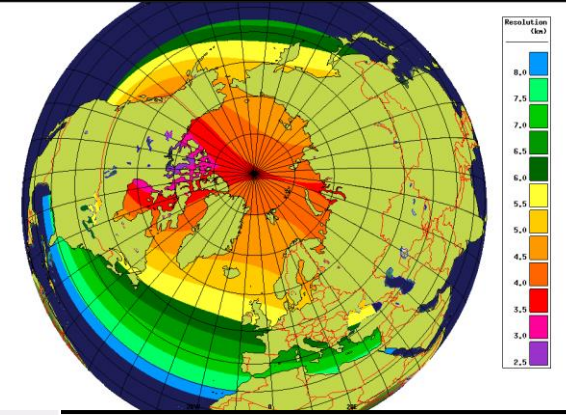
This study has been conducted using E.U. Copernicus Marine Service Information

The code py-eddy-tracker developed by Evan Mason and Antoine Delepoulle

Special thanks to Antoine Delepoulle for answering all our questions

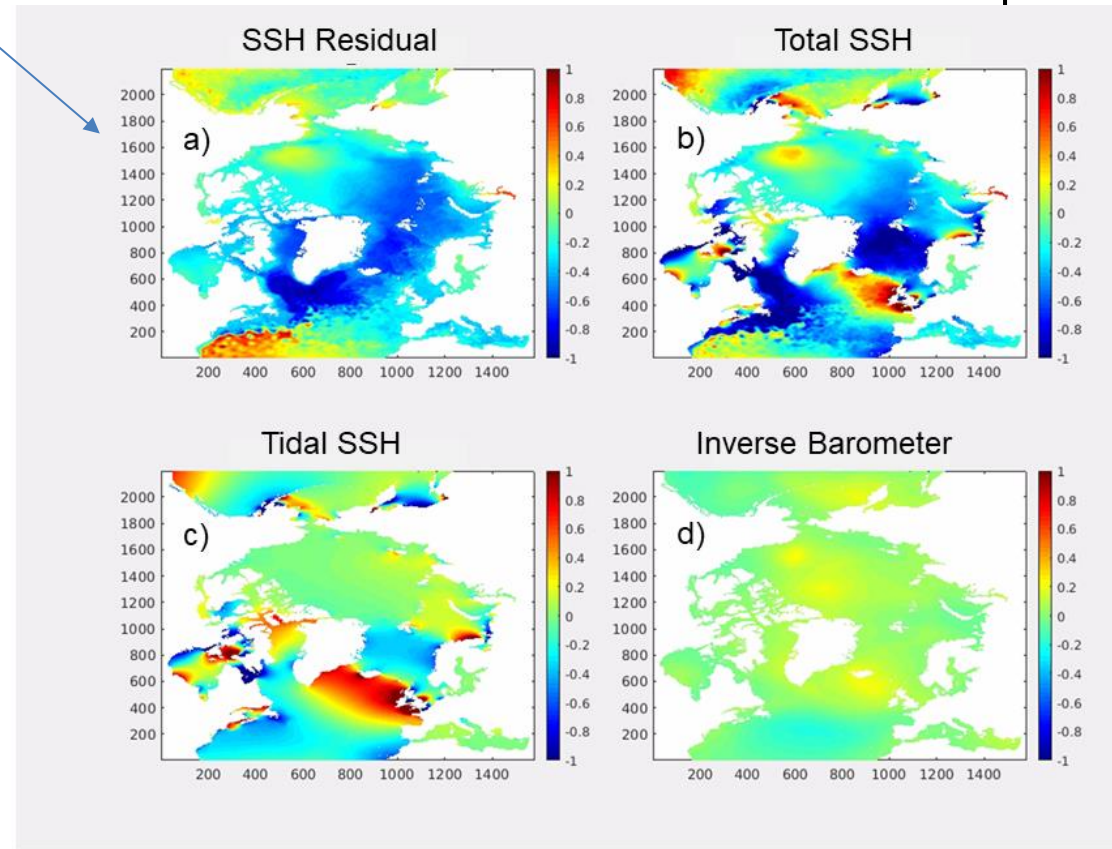


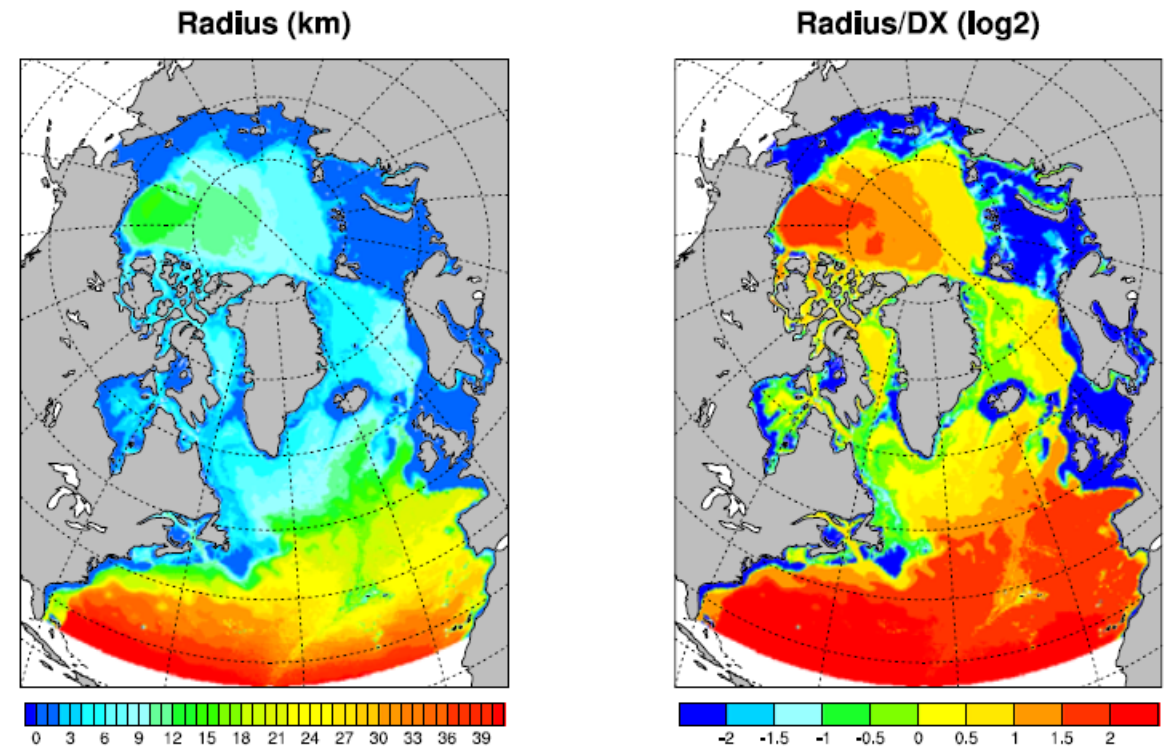
# DATA ASSIMILATION IN RIOPS



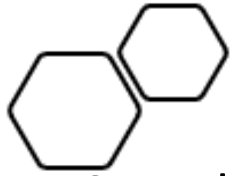
Model resolution

- Produces daily ice-ocean analyses from two successive 7-day cycles
  - 3D bias correction, 7-day IAU
  - Novel online harmonic analysis for tides
  - Atmospheric pressure
- Mercator Ocean Assimilation System (SAM2):
  - Sea surface temperature
  - Temperature and salinity profiles
  - Sea level anomaly from satellite altimeters
- Ocean analysis blended with 3DVar Ice analysis
  - SSM/I, SSM/IS, AVHRR, ASCAT, AMSR2
  - CIS charts, Radarsat image analyses
  - Uses ice analysis error in blending
- Implemented July 2019



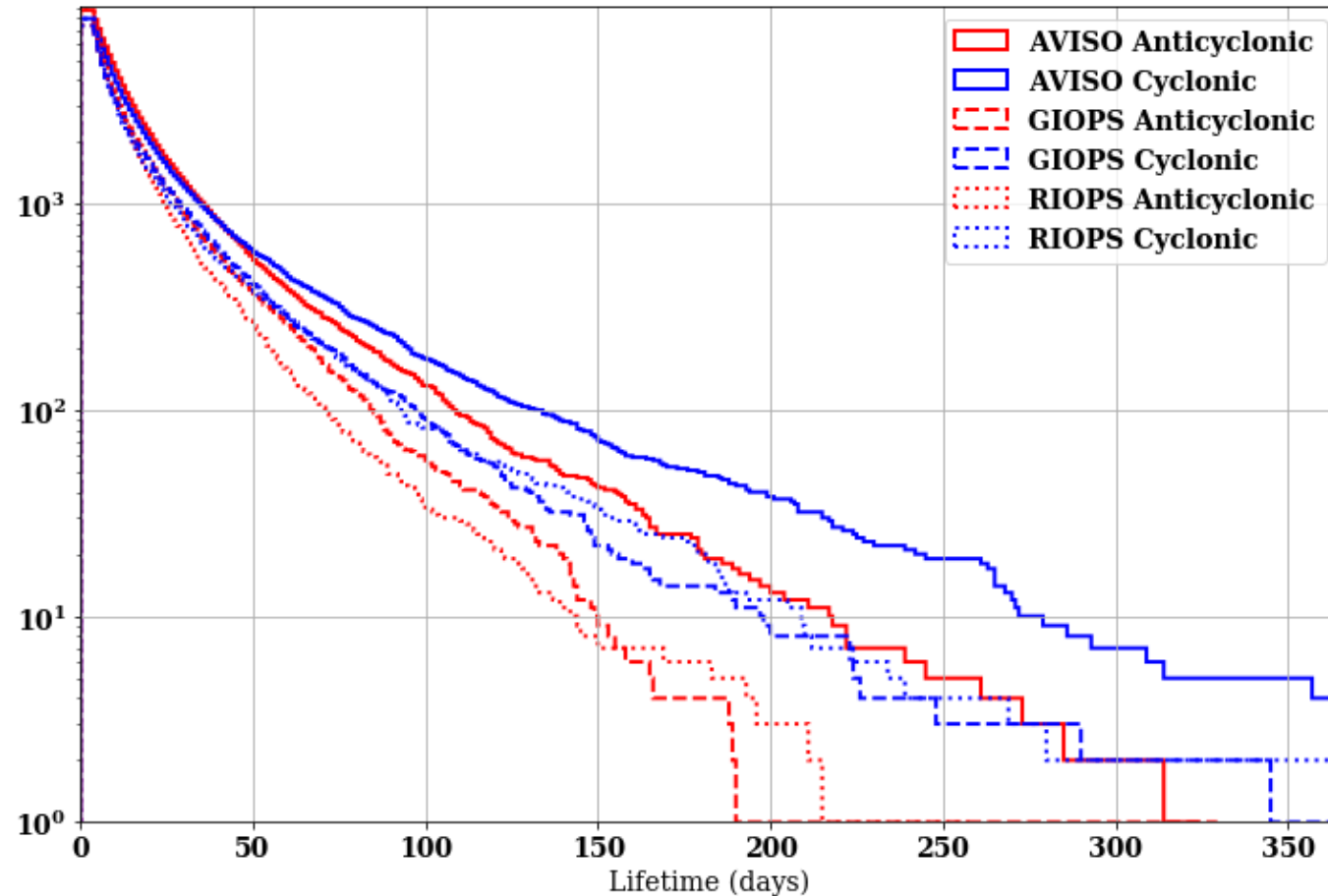


**Figure 2.** First Rossby radius of deformation (left, in kilometres) and Rossby radius relative to the local resolution in log 2 (right). Grossly speaking, the right panel shows where model is eddy resolving (values above 1, that is, 2 model points to resolve a baroclinic eddy), eddy permitting (between 0 and 1) or does not resolve eddies (values below 0.)

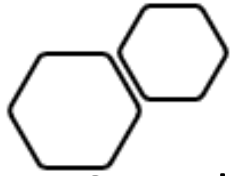


# Supplementary - Eddy Tracking - Lifetimes

Cumulative lifetime for anticyclonic (red) and cyclonic (blue) eddies in the Gulf Stream.







# Supplementary – Eddy Matching

Cumulative histograms of eddies in the Gulf Stream.

